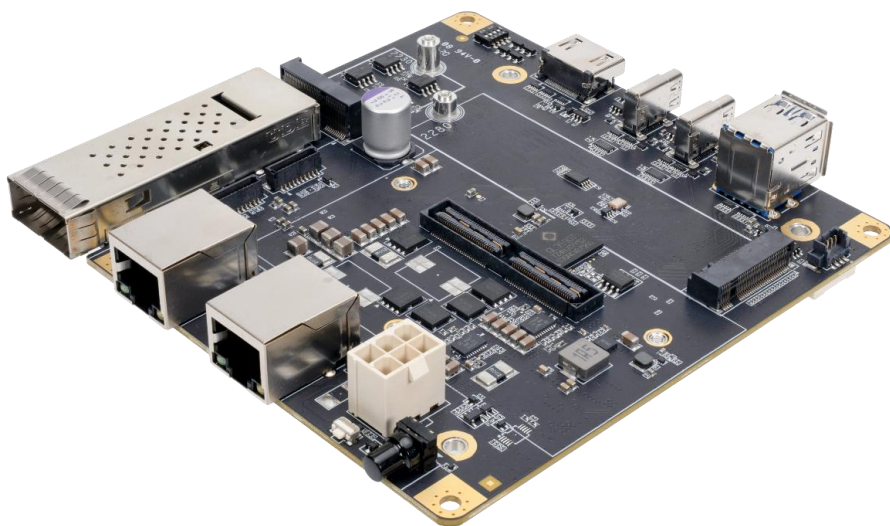


AVerMedia D333

Preliminary

Applies to NVIDIA Jetson T5000™/Jetson T4000™



AVerMedia Technologies, Inc.

No. 135, Jian 1st Rd., Zhonghe Dist., New Taipei City 23585, Taiwan

Tel: 886-2-2226-3630

Fax: 886-2-3234-4842

Sales and Marketing: [Contact](#)

Technical Support: [Professional User](#)

Table of Contents

Preface	2
Disclaimer	2
Technical Support	2
Contact Enquiry	2
Download User Manual	2
Revision History	3
https://www.avermedia.com/professional/contact	4
Product Warranty	5
Copyright Notice	5
Trademark Acknowledgement	6
ESD Warning	6
Safety Precaution:	7
1.0 Introduction	8
1.1 Product Specifications	9
1.2 Product Overview	10
1.3 Connector Summary	12
1.4 Carrier Board Interface	13
2.0 Installation	17
2.1 BSP Setup Instructions	17
3.0 Software	18
4.0 Force Recovery Mode	20
5.0 Accessory Drawings	21
5.1 Power Cord	21

Preface

Disclaimer

The information contained in this user manual, including but not limited to any product specification, is subject to change without notice. AVerMedia assumes no liability for any damage incurred directly or indirectly from any technical or typographical errors or omissions contained herein or for discrepancies between the product and the user manual.

Technical Support

If you experience the difficulty after reading this manual and/or using the product, please contact the reseller from which you purchased the product. In most cases, the reseller can help you with the product installation and the difficulty you encountered.

In case the reseller is not able to resolve your problem, our highly capable global technical support team can certainly assist you. Our technical support section is available 24 hours a day and 7 days a week through our website, with the [click here](#). For more contact information, you may find it in the section of AVerMedia Global Offices.

Contact Enquiry

For more information of our products, pricing, and order placement, please fill in our inquiry form [here](#), we will contact you within 24 hours.

Download User Manual

Please click the link [here](#) to download the file of this user manual from AVerMedia website.

Revision History

Revision	Date	Updates
V0.1	July 13, 2026	1st (D333 MB-A) Preliminary Release

AVerMedia Global Offices

<https://www.avermedia.com/professional/contact>

Headquarters

Taiwan Office

No. 135, Jian 1st Rd., Zhonghe Dist., New Taipei City 23585, Taiwan

Tel:  +886-2-2226-3630

Fax: +886-2-3234-4842

Sales & Marketing: [Contact](#)

Technical Support: [Home users](#) /

[Professional users](#)

The Americas

USA Office

4038 Clipper Court Fremont, CA 94538

Tel:  (510) 403-0006

Fax: (510) 403-0022

Sales & Marketing: [Contact](#)

Technical Support: [Home users](#) /

[Professional users](#)

Brazil Office

Sales & Marketing: [Contact](#)

Technical Support: [Home users](#) /

[Professional users](#)

Latin America Office

Sales & Marketing: [Contact](#)

Technical Support: [Home users](#) /

[Professional users](#)

Europe

Head Office EU

AVT Solutions GmbH

Hanauer Landstrasse 291 B 60314

Frankfurt Hessen

Germany

: technicalsupport_120

Sales & Marketing: [Contact](#)

Technical Support: [Home users](#) /

[Professional users](#)

Russia Office

Sales & Marketing: [Contact](#)

Technical Support: [Home users](#) /

[Professional users](#)

Professional Solutions Support Tel:

 +7 (925) 834-0310

Spain Office

AVerMedia Europe Group

Ronda de Poniente no. 4 segundo H

28760 Tres cantos, Madrid

Spain:

: technicalsupport_120

Sales & Marketing: [Contact](#)

Technical Support: [Home users](#) /

[Professional users](#)

Asia-Pacific

China Office

Room 1510, No.488, Hitech Plaza, South

Wuning Rd., Jingan District, Shanghai,

China

Tel:  +86-021-5298 7985

Fax: +86-021-5298 7981

Sales & Marketing: [Contact](#)

Technical Support: [Home users](#) /

[Professional users](#)

Japan Office

6F, Kojimachi Syuei Bldg. 4-3-13 Kudan-

minami, Chiyoda-ku, Tokyo, 102-0074,

Japan

Sales & Marketing: [Contact](#)

Technical Support: [Home users](#) /

[Professional users](#)

Product Warranty

Please refer to [Support | Warranty And Rma Services | AVerMedia](#)

Copyright Notice

The information contained in this document is subject to change without notice. AVerMedia shall not be liable for errors contained herein or for incidental consequential damages in connection with the furnishing, performance, or use of this material. This document contains proprietary information that is protected by copyright. All rights are reserved. No part of this document may be photocopied, reproduced, or translated to another language without the prior written consent by AVerMedia.

Trademark Acknowledgement

AVerMedia acknowledges all the trademarks, registered trademarks, and/or copyrights referred to in this document as the property of their respective owners. Not listing all possible trademarks or copyright acknowledgments does not constitute the lack of acknowledgment to the rightful owners of the trademarks and copyrights mentioned in this document.

ESD Warning

Electronic components and circuits are sensitive to Electrostatic Discharge (ESD). When handling any circuit board assemblies including AVerMedia products, it is highly recommended that ESD safety precautions can be observed. ESD safe best practices can include but are not limited to the following ones.

1. Leave the circuit board in the antistatic package until it is ready to be installed.
2. Use a grounded wrist strap when handling the circuit board. At a minimum, you need to touch a grounded metal object to dissipate any static charge, which may be present on you.
3. Avoid handling the circuit board in the carpeted areas.
4. Handle the board by the edges and avoid contact with the components.
5. Only handle the circuit boards in ESD safe areas, which may include ESD floor and/or table mats, wrist strap stations, and ESD safe lab coats.

Safety Precaution:

1. All cautions and warnings on the device should be noted.
2. For safety consideration, do NOT open the device if not a qualified service staff.
3. Place the device on a solid surface during installation to prevent falls.
4. Keep the device away from humidity.
5. Do NOT leave this device in an un-controlled environment with temperatures beyond the device's permitted storage temperature to avoid damage.
6. All adaptors and cables supplied by AVerMedia are verified. Do NOT use any others not supplied by AVerMedia to avoid any malfunction or fires.
7. Make sure the power source matches the power rating of the device.
8. Place the power cord where people cannot step on it. Do not put anything on the power cord.
9. Always completely disconnect the power while the device is not used or idle for a long time.
10. Disconnect the device from any AC supply before cleaning. While cleaning, use damp cloth instead of liquid or spray detergents.
11. Make sure the device is installed near a power outlet and easy for accessibility.
12. Do not cover the openings on the device to ensure optimal heat dissipation.
13. Watch out the heatsink or heat spreader of the device when the system is running.
14. Never pour any liquid into the openings. This could cause fire or electrical shock.
15. The static electricity should be noted while installing any internal components. Consider using a grounding wrist strap and put all electronic parts in static-shielded containers.

If the following situations occur, please contact our service personnel:

- (1) The device is dropped or damaged
 - (2) Damaged power cord or plug
 - (3) Exposure to moisture
 - (4) Liquid intrusion into the device
 - (5) Any obvious signs of damage displayed on the device
 - (6) The device is not working as expected or in a manner as described in this manual
16. The static electricity should be noted while installing any internal components. Consider to

1.0 Introduction

AVerMedia's carrier board D333 is a compact edge supercomputing design that supports the powerful NVIDIA Jetson T5000™/ Jetson T4000™. The D333 series delivers exceptional AI computing performance, rich I/O expandability, and industrial-grade reliability for demanding edge AI workloads.

Optimized for humanoid robots and autonomous mobile robots (AMRs), the D333 Thor platform is a high-performance carrier board designed to enable real-time sensor fusion and ultra-low-latency motion control. It supports the concurrent execution of multiple AI models, enabling seamless integration of vision, speech, and decision-making capabilities for advanced autonomous and multimodal AI systems.

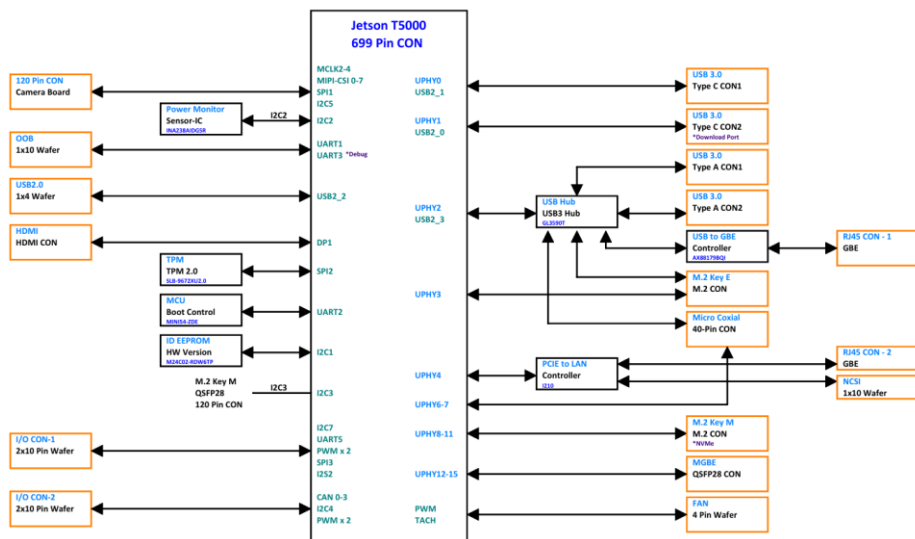
The D333 is compatible with AVerMedia's daughter boards, including GMSL, PoE, and USB modules, enabling flexible system expansion and faster solution integration.

With PCIe Gen5 expansion, an efficient thermal design, and seamless integration with the latest NVIDIA JetPack SDK, the D333 Thor series provides a unified foundation for scalable, vision-centric AI solutions, making it an ideal carrier board for next-generation AI system integration.

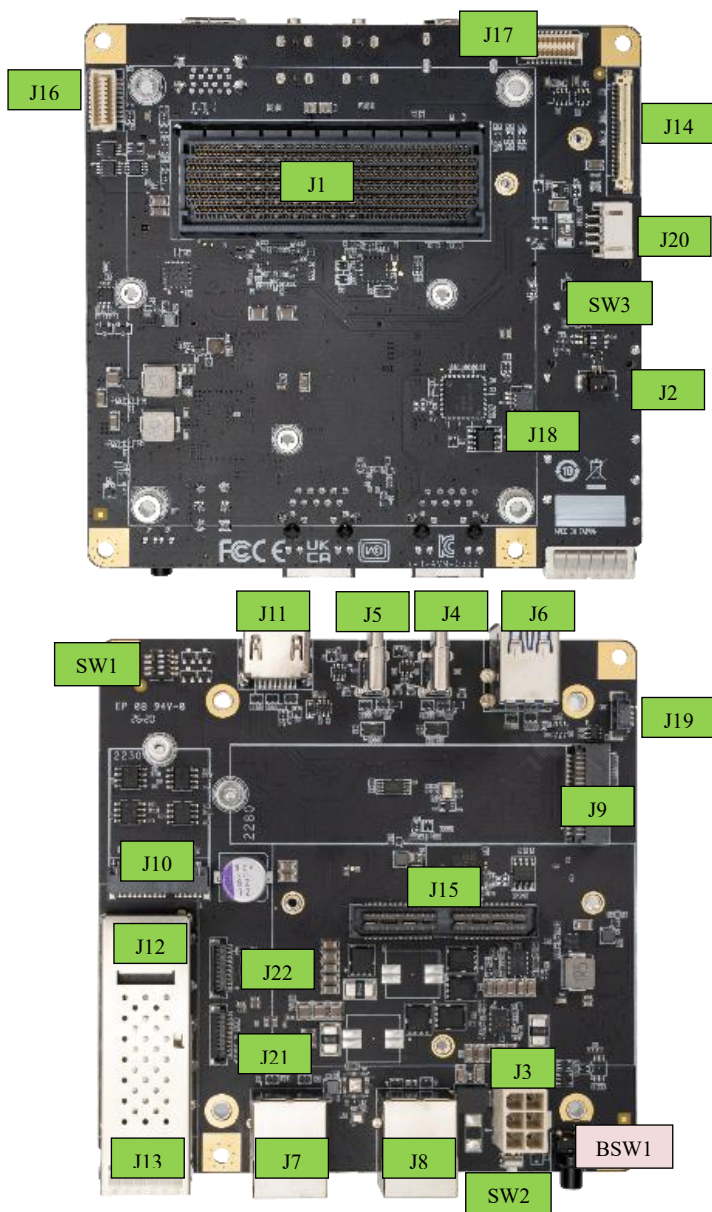
1.1 Product Specifications

NVIDIA Jetson SoM	NVIDIA Jetson T5000™/Jetson T4000™
Networking	• 2x GbE RJ-45 (1× port supports OOB NCSI for optional OOB module) • 1x QSFP (4× 10 GbE for JetPack 7.1 / 4 x 25 GbE for JetPack 7.2) • 1x M.2. key E 2230 for Wi-Fi 6
Display Output	1x HDMI output (3840 x 2160 at 60Hz)
Temperature	• Operating temperature: -40 to 85°C (carrier board) • Storage temperature -40°C ~ 85°C • Relative humidity 40 °C @ 95%, Non-Condensing
Camera Input	1x 120pin for GMSL camera board
USB	• 1x USB 3.2 Type-C for BSP install • 1x USB 3.2 Type-C (Data Host-only) • 2x USB 3.2 Type-A • Optional 8x USB3.2 Type-A (via daughter board) TBD
Storage	1x NVMe M.2 Key M 2280
TPM	TI SLB9672XU2.0 on board
Expansion Header	• 20pin expansion header-1: 1x I2C, 1x I2S, 1x SPI, 2x GPIO(PWM), 1x UART, +5V output 1A, +3.3V output 1A • 20pin expansion header-2: 4x CAN-FD, 1x I2C, 2x GPIO(PWM), +5V output 1A, +3.3V output 1A • 1x 40pin coaxial connector for PCIe expansion (daughter board 8xPoE or 8xUSB) TBD
Power requirement	ATX 6pin 12~36V DC Input
Thermal Solution	1x SOM FAN
Buttons	Power and Recovery
RTC Battery	Support RTC Battery and Battery Life Monitoring by MCU
Dimensions	W: 120mm x L: 120mm / Weight: 120g
Certifications	CE, FCC,VCCI, KC (TBA)
GPS	1x internal USB wafer for Optional Dual-RTK GNSS support (via daughter board)
Sensor	Temperature sensor
LED	1x system power
Package	1x Carrier board 2x GPIO board 1x Adapter

1.2 Product Overview



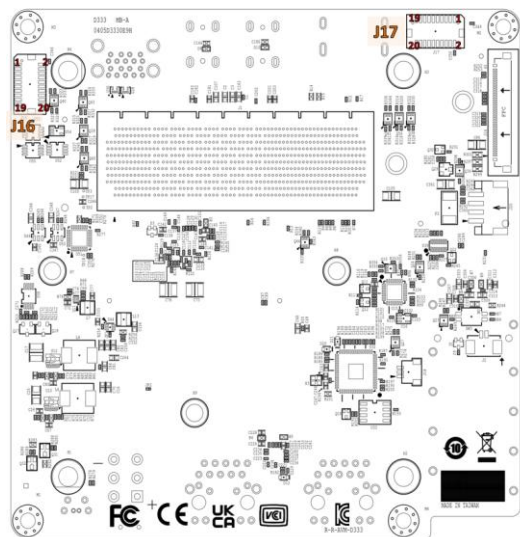
Front View and Back View of Carrier board



1.3 Connector Summary

J1	699-pin high-speed/high-density connector
J17	20pin Expansion I/O Connector - 2
J16	20pin Expansion I/O Connector - 1
J20	Fan Wafer
J2	External RTC Battery wafer
J18	Debug UART
J19	GNSS Expansion Board
J22	OOB Connector
J21	OOB (NCSI Connector)
J3	Input Power – 4.2mm Pitch ATX Power 6P
J11	HDMI output Type-A Vertical Side Connector (Female)
J5	USB 3.2 Gen1 Type C Connector (supports Nvidia Jetson flashing)
J4	USB 3.2 Gen2 Type C Connector (Data Host-only)
J6	USB 3.2 Gen2 Type A Connector x2
J10	M.2 E-Key 2230 Socket
J9	M.2 M-Key 2280 Socket
J7	Gigabit Ethernet Connector w/LEDs
J8	Gigabit Ethernet Connector w/LEDs
J14	40-pin Expansion Coaxial Connector
J15	120-pin high speed board to board connector (to Camera board)
J12	QSFP28 Connector
BSW1	Power Button w/LEDs
SW1	CAN BUS Terminator Switch
SW2	Recovery Button
SW3	Boot Function Switch

1.4 Carrier Board Interface

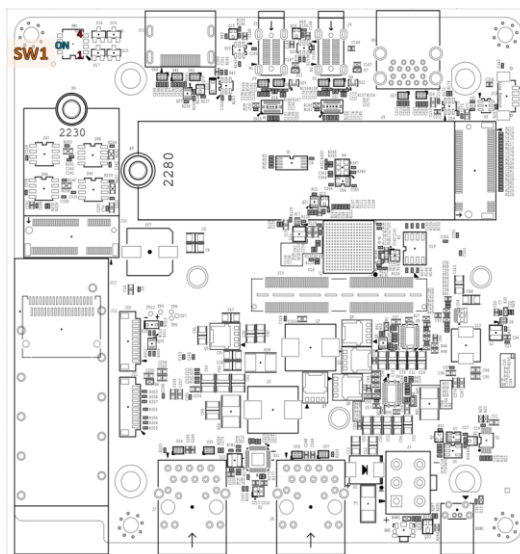


Expansion I/O Connector - 1

J16 佳龍電子 (CSE)			BM20B-SHLD5-G-TFT(LF)(SN)		
Pin	Net Name	SOM Pin	Pin	Net Name	SOM Pin
1	3.3V		2	SV	
3	GND		4	GND	
5	I2C_GP11_DAT_3V3	E26	6	UART5_TX_3V3	J58
7	I2C_GP11_CLK_3V3	E27	8	UART5_RX_3V3	H58
9	GPIO36_PWM3_3V3	F56	10	GND	
11	GPIO44_PWM5_3V3	E5	12	SPI3_SCK_3V3	F55
13	I2S2_SCLK_3V3	G4	14	SPI3_MISO_3V3	D56
15	I2S2_SDOUT_3V3	F5	16	SPI3_MOSI_3V3	G56
17	I2S2_SDIV_3V3	F6	18	SPI3_CS0_3V3	C57
19	I2S2_LRCK_3V3	E4	20	SPI3_CS1_3V3	E56

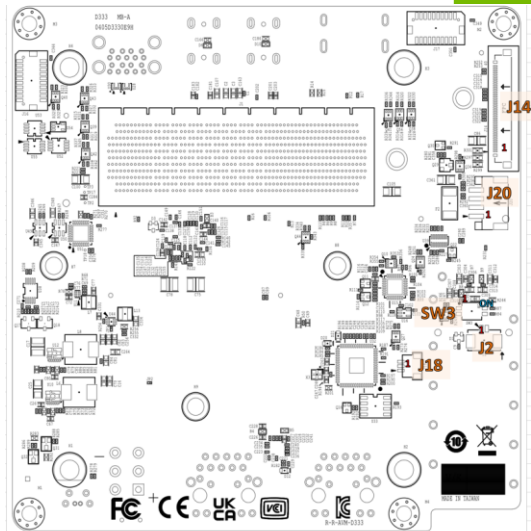
Expansion I/O Connector - 2

J17 佳龍電子 (CSE)			BM20B-SHLD5-G-TFT(LF)(SN)		
Pin	Net Name	SOM Pin	Pin	Net Name	SOM Pin
1	3.3V		2	SV	
3	GND		4	GND	
5	GPIO27_PWM2_3V3	H52	6	I2C_GP8_DAT_3V3	E60
7	I2S7_LRCK_PWM10_3V3	L49	8	I2C_GP8_CLK_3V3	D61
9	GND		10	GND	
11	CANL2		12	CANL0	
13	CANH2		14	CANH0	
15	GND		16	GND	
17	CANL3		18	CANL1	
19	CANH3		20	CANH1	



CAN BUS Terminator Switch

SW1 DIPTRONICS		DHN-04F-T-Q-T/R	
Pin	ON = Enable Terminator	SOM Pin	
1	CAN0		
2	CAN1		
3	CAN2		
4	CAN3		



40-pin Expansion Coaxial Connector

J14	I-PEX	20455-040E-12			
Pin	Net Name	SOM Pin			
1	VDD_Coaxial				
2	VDD_Coaxial				
3	VDD_Coaxial				
4	VDD_Coaxial				
5	VDD_Coaxial				
6	VDD_Coaxial				
7	GND				
8	GND				
9	GNSS_CTRL	J5			
10	AIRPLANE_CTRL	E6			
11	LTE_PWR	H5			
12	PCIe_WAKE_N	A8			
13	PCIe_C3_CLKREQ_N	G8			
14	PCIe_C3_RST_N	J9			
15	GND				
16	USBSS_DSP_Y_TX_P				
17	USBSS_DSP_Y_TX_N				
18	GND				
19	USBSS_DSP_Y_RX_P				
20	USBSS_DSP_Y_RX_N				
21	GND				
22	USB2_DSP_Y_DP				
23	USB2_DSP_Y_DM				
24	GND				
25	PCIe_C3_UPHY0_TX7_P	H12			
26	PCIe_C3_UPHY0_TX7_N	H13			
27	GND				
28	PCIe_C3_UPHY0_TX6_P	K13			
29	PCIe_C3_UPHY0_TX6_N	K12			
30	GND				
31	PCIe_C3_UPHY0_RX7_P	D12			
32	PCIe_C3_UPHY0_RX7_N	D13			
33	GND				
34	PCIe_C3_UPHY0_RX6_P	B12			
35	PCIe_C3_UPHY0_RX6_N	B13			
36	GND				
37	PCIe_C3_CLK_P	E23			
38	PCIe_C3_CLK_N	E22			
39	GND				
40	SG_RST				

FAN

J20	宏致電子 (ACES)	50224-00301-001			
Pin	Net Name	SOM Pin			
1	GND				
2	+12V_SOM_FAN				
3	FAN_TACH	E54			
4	FAN_PWM	K62			

Boot Function Switch

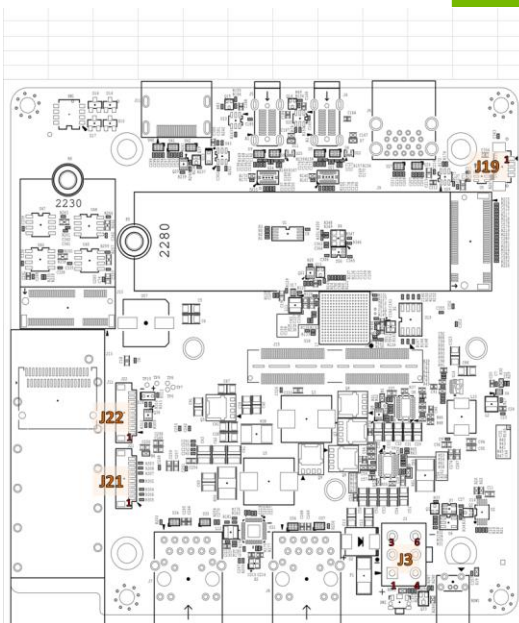
SW3	CHAMPWAY	NDSVM-02Q-T-R			
Pin	Net Name				
1	ON=>Button Power				
	OFF=>Auto Power				
2	ON=>Always On Enable				
	OFF=>Always On Disable				

RTC Coin Cell Battery

J2	宏致電子 (ACES)	50271-00201-001			
Pin	Net Name	SOM Pin			
1	GND				
2	RTC_BAT				

Debug UART

J18	宏致電子 (ACES)	50224-00301-001			
Pin	Net Name	SOM Pin			
1	UART3_TX_DEBUG_3V3	H62			
2	GND				
3	UART3_RX_DEBUG_3V3	K60			



GNSS Expansion Board

J19 宏致電子 (ACES)			50279-00471-001		
Pin	Net Name	SOM Pin			
1	+5V_GNSS				
2	USB2.0_DP1	A10			
3	USB2.0_DM1	A11			
4	GND				

OGB Connector

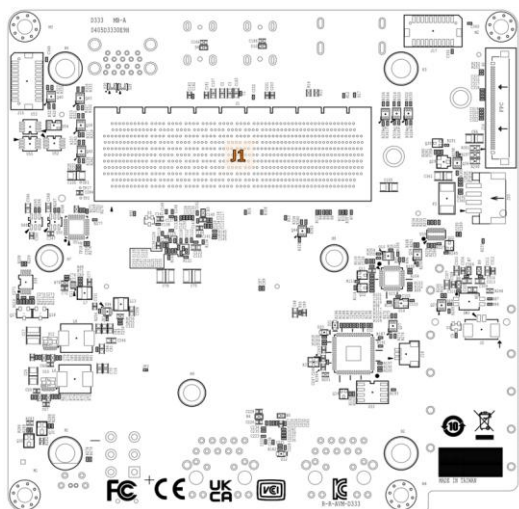
J22 宏致電子 (ACES)			50228-01071-001		
Pin	Net Name	SOM Pin			
1	GND				
2	X				
3	UART3_RX_DEBUG_3V3	K60			
4	UART3_TX_DEBUG_3V3	H62			
5	UART1_RX_3V3	KS4			
6	UART1_TX_3V3	KS3			
7	+5V_SOM_PG				
8	/RESET_IN	L60			
9	/POWER_BTN				
10	+5V_SYSTEM				

NCSI Connector

J21 宏致電子 (ACES)			50228-01071-001		
Pin	Net Name	SOM Pin			
1	NC_SI_TXD0				
2	NC_SI_TXD1				
3	NC_SI_TX_EN				
4	GND				
5	NC_SI_CLK_IN				
6	GND				
7	NC_SI_RXD0				
8	NC_SI_RXD1				
9	NC_SI_CRS_DV				
10	GND				

DC Input

J3 宏致電子 (ACES)			56973-0060N-001		
Pin	Net Name	SOM Pin	Pin	Net Name	SOM Pin
1	VDD_DCIN		4	GND	
2	VDD_DCIN		5	GND	
3	VDD_DCIN		6	GND	



699-Pin SOM Connector

J1		Molex	203456-0003
Mirror Mezz Hermaphroditic Connector, 5.50mm 699 Circuits, 0.76µm Gold (Au) Pla			

HDMI OUTPUT

J11	志展實業 (Compupack)	ACNHM220028-001
HDMI A TYPE 19P R/A SMT H6.20mm		

Type C CON1

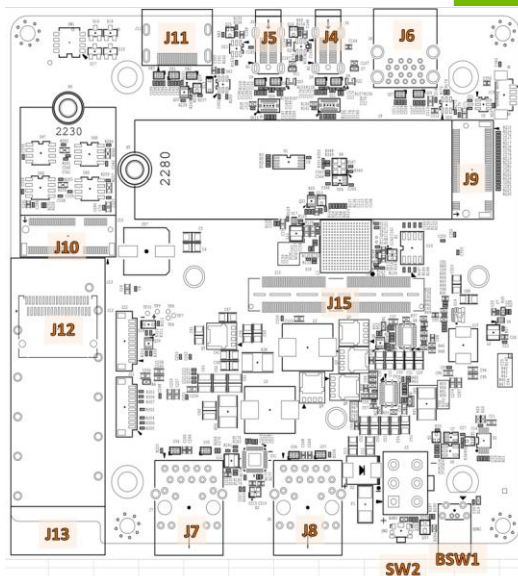
J5	建倫科技 (Contact)	SBC-240P-31HF-S277
USB 3.2 Type C SMT Upright Side *Flashing Port		

Type C CON2

J4	建倫科技 (Contact)	SBC-240P-31HF-S277
USB 3.2 Type C SMT Upright Side		

Type A CON x 2

J6	Champway Electronics	CU3B-AFR15U-096H
JACK_USB3*2_A TYPE(F)_90°_DIP		



M.2 E Key 2230

J10 东微电子 (ACES) S1748-07502-005
SOCKET M.2-KEY E_75PIN_90°_SMD

M.2 M key 2280

J9 Amphenol 10187495-MSRHLF
SOCKET M.2-KEY M_75PIN_90°_SMD

120-Pin Connector (to Camera Board)

J15 SAMTEC QSH-060-01-L-D-A-K-TR
WAFER_2*60PIN_0.5mm_180°_SMD

QSFP28 Connector

J12 沛德电子 (U.D. Electronic) SZ01-ZZ-0001
QSFP28 Connector (Style A) Right Angle SMT

QSFP28 Connector

J13 沛德电子 (U.D. Electronic) SZ10-ZZ-0005
QSFP28 Cage 1X1 (Style A)

Gigabit Ethernet Connector - 1

J7 建尚科技 (Contact) MJ45-111QC4A-GY-S307
RJ45 W/TRANSFORMER 100/1000 BASE W/LED

Gigabit Ethernet Connector - 2

J8 建尚科技 (Contact) MJ45-111QC4A-GY-S307
RJ45 W/TRANSFORMER 100/1000 BASE W/LED

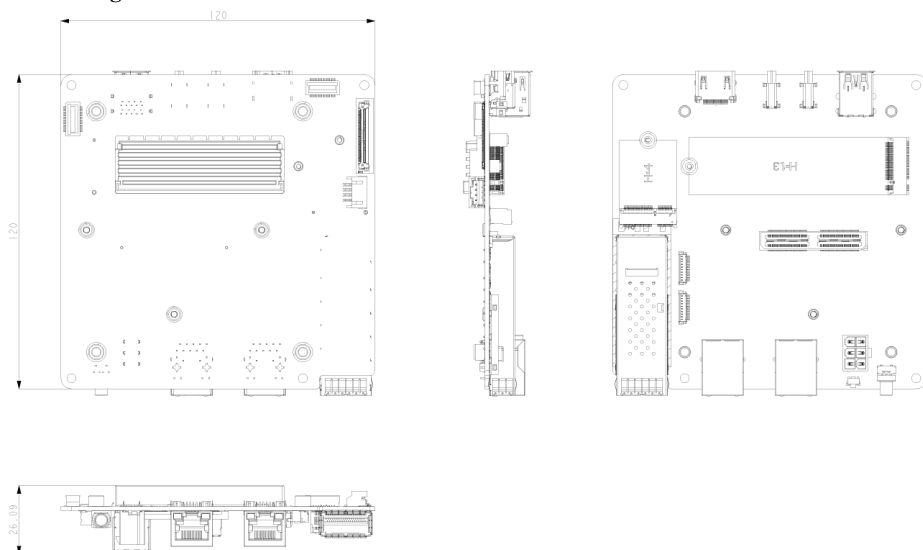
Recovery Button

SW2 Champway Electronics TS104A2ME-035WBR-R
TACH SWITCH Right Angle SMD

Power Button

BSW1 Champway Electronics LS67AK-NBR-A-R2KA9
Button_LED_DIP-90°

2D drawing



2.0 Installation

- Check and ensure all external system power supplies are turned off.
 - Connect the power cord to CB/devkit/Box PC DC in jack or ATX 6pin
 - Connect the USB Type-C cable to CB/devkit/Box PC connector.
 - Press and hold on the Recover button
 - Plug in AC power
- (Since the DCINJACK is slightly tight, be careful not to shake it when inserting the CB/devkit/Box PC)

2.1 BSP Setup Instructions

BSP (board support package) file: AVERMEDIA_JETPACK-R2.*.*.*_desktop.tar.gz for D333

If you want to get the BSP download link, please contact AVerMedia FAE.

Default login username/password of the BSP is nvidia/nvidia

If you have difficulties to access the BSP download link, please visit AVerMedia website at <https://www.avermedia.com/professional/download>, or contact technical support at https://www.avermedia.com/professional/technical_support or e-mail us at esusupport@avermedia.com for further assistance.

BSP Installation steps for NVIDIA Jetson board: (Important Note: Please backup your personal files before re-flashing BSP)

After you download the BSP file and put the file in a Linux PC, please refer to the steps below to re-flash BSP.

1. Let the JETSON AGX Thor initiate recovery mode.

You have to keep pressing “Recovery” button and then power on the NVIDIA Jetson board to initiate recovery mode.

When connecting a NVIDIA Jetson board to a Linux PC via a USB Type-C to USB cable, you can check kernel messages with ‘dmesg’ command in the Linux PC.

Once you see similar messages as below, it means that the NVIDIA Jetson board is in the recovery mode.

```
[24685.229129] usb 1-7: Product: APX
```

```
[24685.229132] usb 1-7: Manufacturer: NVIDIA Corp
```

2. Using the commands below in the Linux PC to start re-flashing BSP.

sudo is required to extract BSP

\$ sudo tar zxvf AVERMEDIA_JETPACK- R2.*.*.*_desktop.tar.gz

\$ cd JetPack_*.**_desktop/Linux_for_Tegra

\$ installation steps: refer to AVERMEDIA_JETPACK- R2.*.*.*_ReleaseNote.txt

3.0 Software

This section describes BSP's features for D333

1. Support optional M.2 WI-FI/Bluetooth modules (Intel® Wireless-AX210), the manager UI of AX210 WiFi/Bluetooth is located on the upper-right corner of Ubuntu desktop. It can be also controlled by nmcli/bluetoothctl in command line.
2. Power Mode
Power mode can be modified by the UI on the upper-right corner of Ubuntu or the following commands.

```
# get current power mode
$ sudo nvpmodel -q
# setup power mode
# where <x> is power mode number, please refer to
https://docs.nvidia.com/jetson/archives/r38.4/DeveloperGuide/SD/PlatformPowerAndPerformance/JetsonThor.html#supported-power-states for more
information
$ sudo nvpmodel -m <x>
```

RTC Battery

The following command can get RTC battery voltage.

```
$ sudo avt tool -a | grep -oP "AIN5.*\[\K[^\]]*"
```

3. Fan Speed

The following commands can get PWM fan information.

```
# get current speed setting of PWM Fan (0 ~ 255)
$ cat /sys/devices/platform/pwm-fan/hwmon/hwmon<x>/pwm1

# get Fan RPM value
$ cat /sys/class/hwmon/hwmon<y>/rpm
```

* Where <x> and <y> are dynamic hwmon indexes.

4. CAN Bus (removed to daughter board)
5. Camera (removed to daughter board)
6. GPIO usage

(1) Locate the GPIO Pin:

Use the `gpiofind` command to determine the pin's location in the system. For example,

to locate the SODIMM Pin 99, which corresponds to PX.04, execute:

```
$ sudo gpiofind PX.04
```

```
# This command will return the GPIO chip and offset. For example, it might return  
gpiochip0 118, indicating that PX.04 is at offset 118 on gpiochip0
```

(2) Set the GPIO Pin Voltage:

Set High Voltage: To set the pin to a high voltage (logic level 1), use the following command:

```
$ sudo gpiowrite --mode=wait 0 118=1
```

Set Low Voltage: To set the pin to a low voltage (logic level 0), use this command:

```
$ sudo gpiowrite --mode=wait 0 118=0
```

For L4T (Linux for Tegra) BSP support and the other software support associated with NVIDIA® Jetson AGX Thor, please visit AVerMedia website to contact our technical support function. (<https://www.avermedia.com/tw/support/contact>)

4.0 Force Recovery Mode

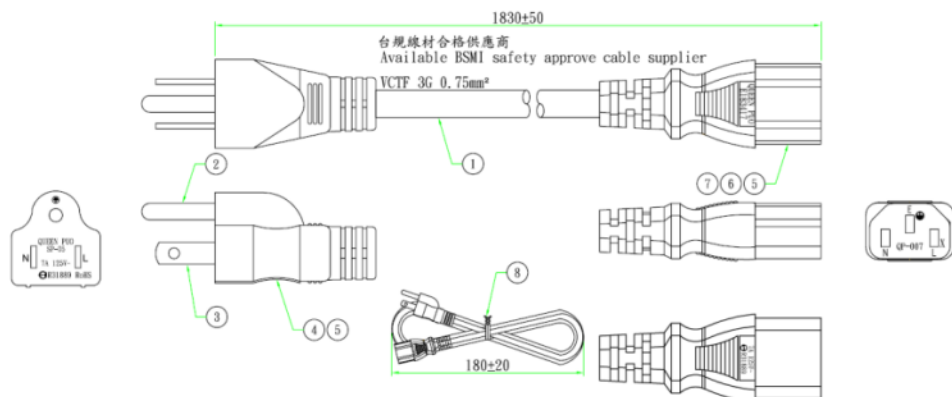
USB Type-C port (J5) of D333 can be used to re-program NVIDIA® Jetson AGX Thor by using the other host system running NVIDIA Jetpack, as the procedure described below.

1. Before you start
 - Please make sure to use a Linux host PC with Ubuntu 22.04 or 20.04 operating system.
 - Please use a native setup (no virtual machine) installation file in the following steps.
 - You will also need a high-quality standard USB Type C connector.
 - Download installation file from Avermedia.
2. Connect carrier board to host PC
3. Connect the system to the Linux host PC. Please use a USB Type C cable (J5 on the carrier board).
4. After connecting to the host PC powering up the system. The system will detect the host PC and automatically enter the flashing state (also called force recovery mode).
5. Check that the connection is established with the `lsusb` command. You should find one entry with Nvidia Corp. as highlighted below.
6. Flashing of system
 - Use the flash cmd script in the extracted bootloader folder to transfer the software into the Jetson compute module and flash it.
 - Please connect a monitor to the system. After the flashing process has completed the should automatically boot and show the Ubuntu desktop.
 - You now have a functioning system ready for your needs.

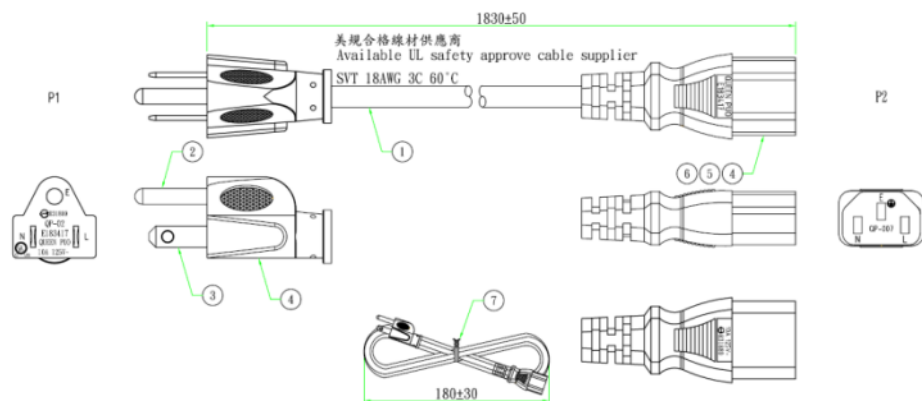
5.0 Accessory Drawings

5.1 Power Cord

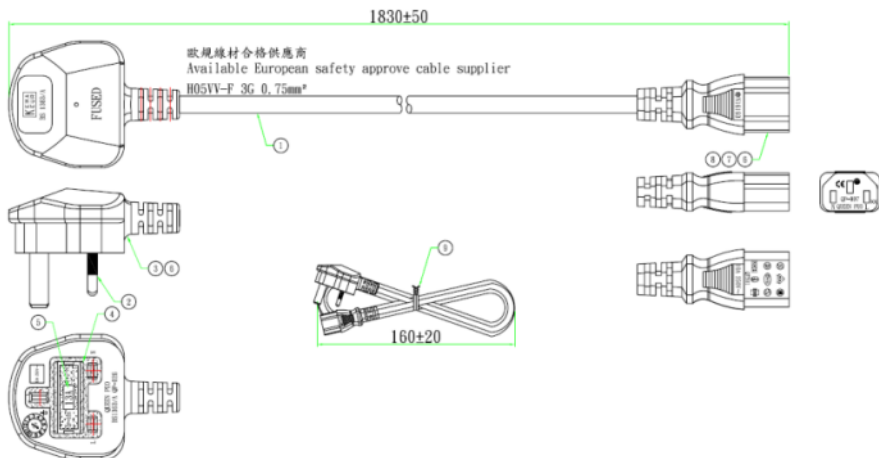
64APOWBRX-IPD (TW version)



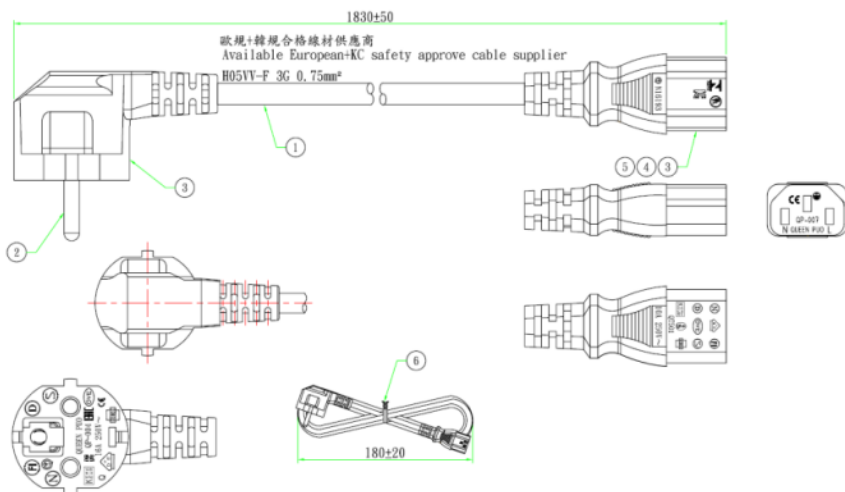
064APOWBR2-IPD (US version)



064APOWBRW-IPD (UK version)



064APOWBR5-IPD (EU version)



Dd 064APOWBR4-IPD (CN version)

